

# Graduate AI

Lecture 11:

Learning Theory

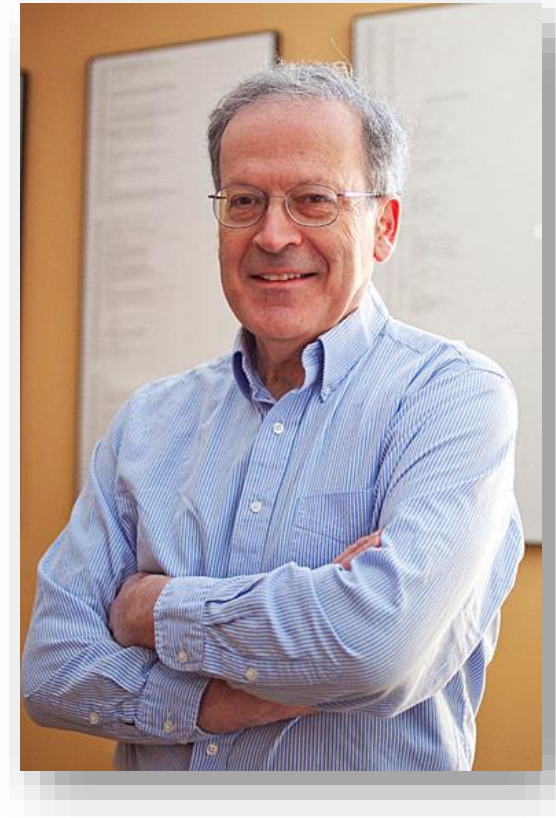
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# THE PAC MODEL

- **PAC** = probably approximately correct
- Introduced by Valiant [1984]
- Learner can do well on training set but badly on new samples
- Establish guarantees on accuracy of learner when **generalizing** from examples

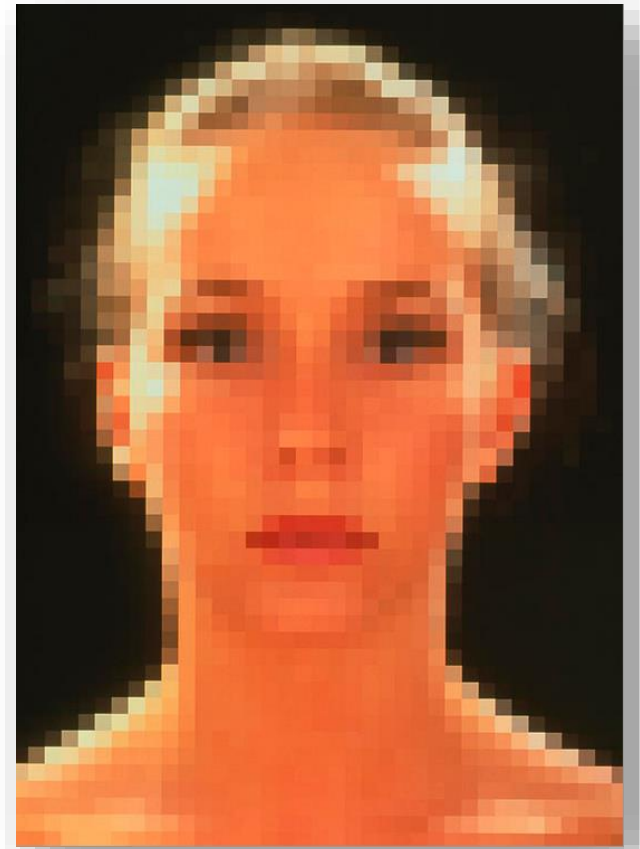


# THE PAC MODEL

- Input space  $X$
- $D$  distribution over  $X$ : unknown but fixed
- Learner receives a set  $S$  of  $m$  instances  $x_1, \dots, x_m$ , independently sampled according to  $D$
- Function class  $F$  of functions  $f: X \rightarrow \{+, -\}$
- Assume target function  $f_t \in F$
- Training examples  $Z = \{(x_i, f_t(x_i))\}$

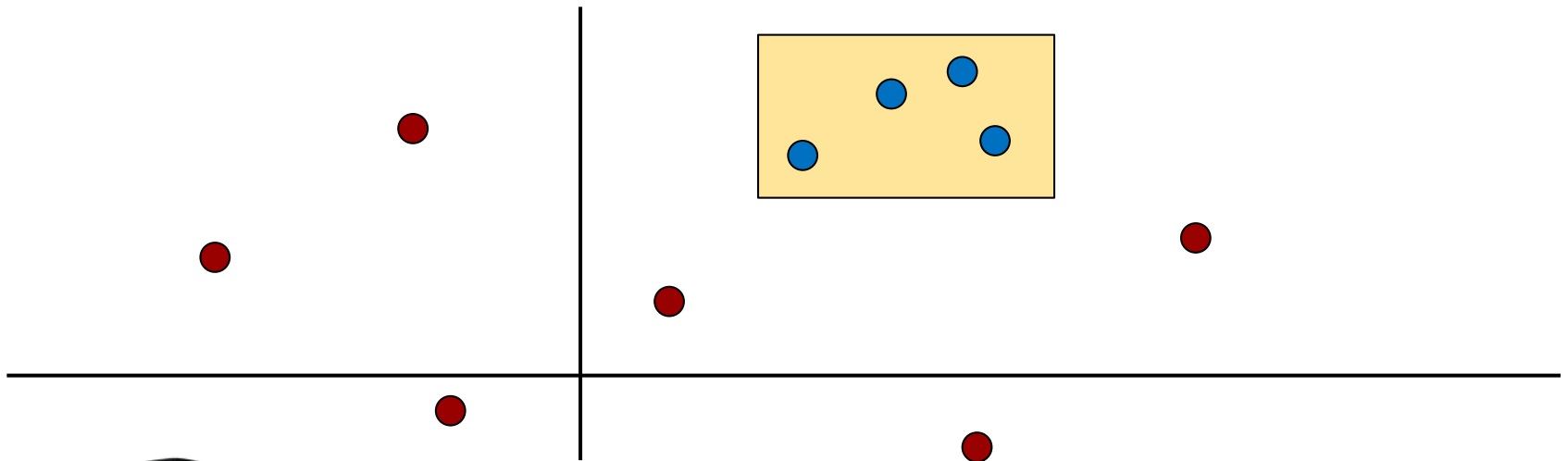
# EXAMPLE: FACES

- $X = \mathbb{R}^{k \times \ell}$
- Each  $x \in X$  is a matrix of colors, one per pixel
- $f_t(x) = +$  iff  $x$  is a picture of a face
- Training examples: Each is a picture labeled “face” or “not face”



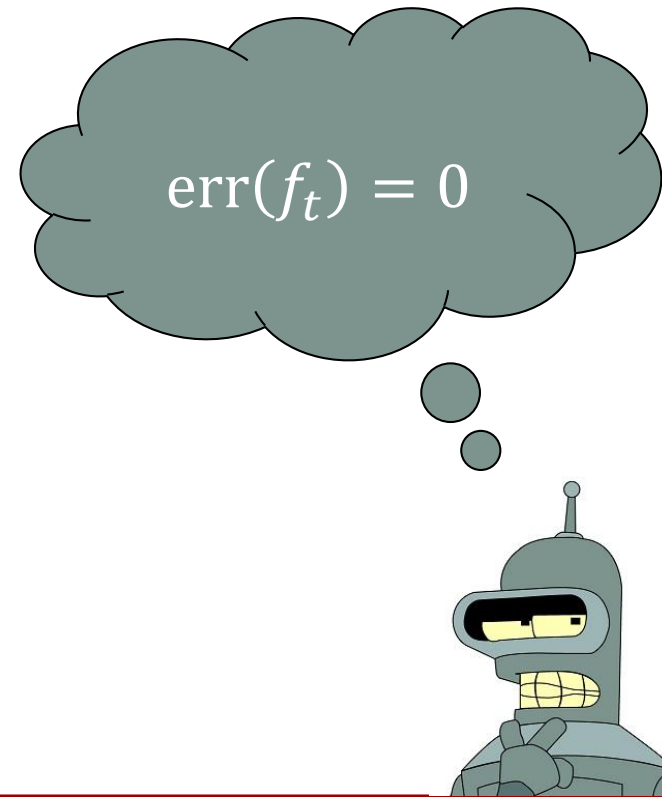
# EXAMPLE: RECTANGLE LEARNING

- $X = \mathbb{R}^2$
- $F =$  axes-aligned rectangles
- $f(x) = +$  iff  $x$  is contained in  $f$



# THE PAC MODEL

- The **error** of function  $f$  is
$$\text{err}(f) = \Pr_{x \sim D} [f_t(x) \neq f(x)]$$
- Given **accuracy** parameter  $\epsilon > 0$ , would like to find function  $f$  with  $\text{err}(f) \leq \epsilon$
- Given **confidence** parameter  $\delta > 0$ , would like to achieve  $\Pr[\text{err}(f) \leq \epsilon] \geq 1 - \delta$



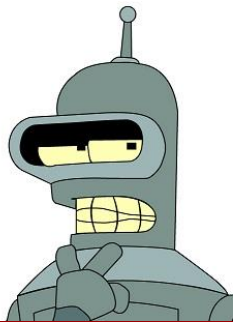
# THE PAC MODEL

- A **learning algorithm**  $L$  is a function from training examples to  $F$  such that: for every  $\epsilon, \delta > 0$  there exists  $m^*(\epsilon, \delta)$  such that for every  $m \geq m^*$  and every  $D$ , if  $m$  examples  $Z$  are drawn from  $D$  and  $L(Z) = f$  then

$$\Pr[\text{err}(f) \leq \epsilon] \geq 1 - \delta$$

- $F$  is **learnable** if there is a learning algorithm for  $F$

$m^*(\epsilon, \delta)$  is  
independent of  $D$ !



# RECTANGLES ARE LEARNABLE

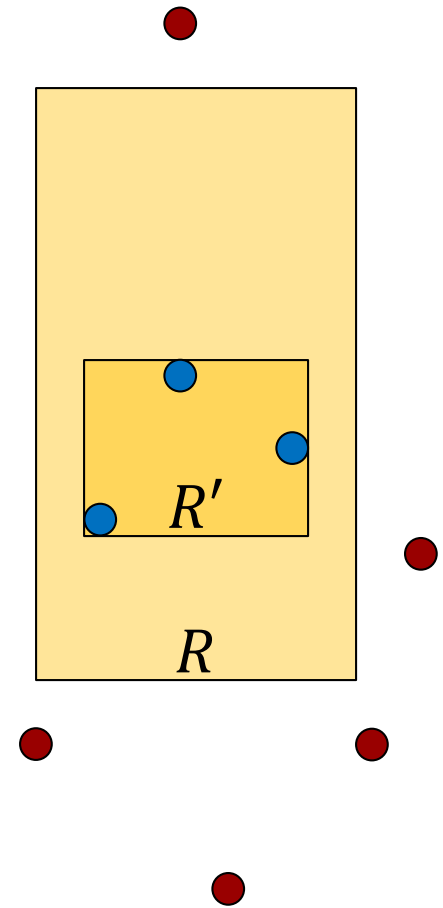
- $X = \mathbb{R}^2$
- $F =$  axes-aligned rectangles
- **Learning algorithm:** given training set, return tightest fit for positive examples
- **Theorem:** axes-aligned rectangles are learnable with **sample complexity**

$$m^*(\epsilon, \delta) \geq \frac{4}{\epsilon} \ln \frac{4}{\delta}$$



# RECTANGLES ARE LEARNABLE

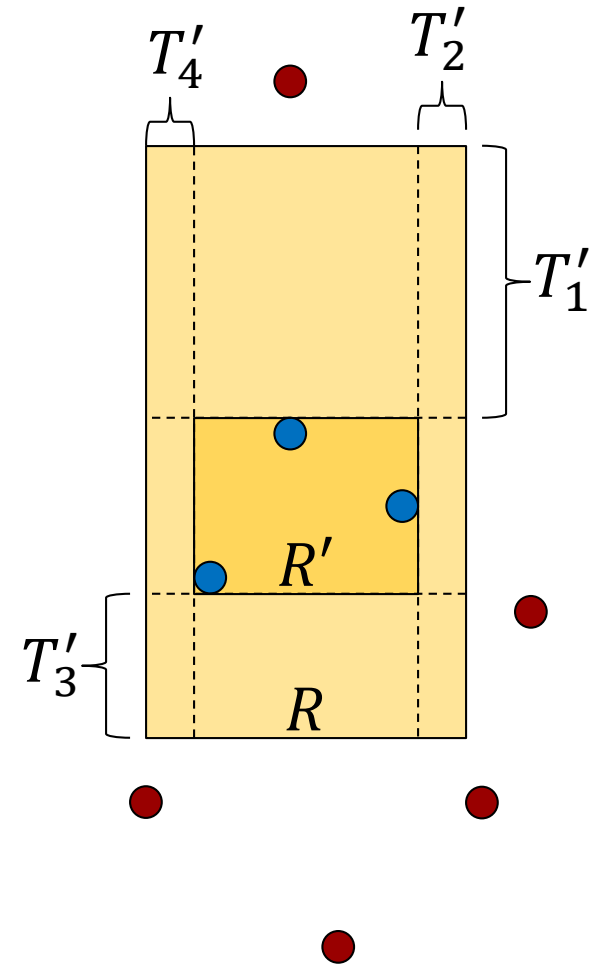
- Proof:
  - Target rectangle  $R$
  - Recall: our learning algorithm returns the **tightest-fitting**  $R'$  around the positive examples
  - For region  $E$ , let
$$w(E) = \Pr_{x \sim D} [x \in E]$$
  - $\text{err}(R') = w(R \setminus R')$  (**why?**)



# RECTANGLES ARE LEARNABLE

- Proof (cont.):
  - Divide  $R \setminus R'$  into four strips  $T'_1, T'_2, T'_3, T'_4$
  - $\text{err}(R') \leq \sum_{i=1}^4 w(T'_i)$
  - We will estimate

$$\Pr \left[ w(T'_i) > \frac{\epsilon}{4} \right]$$



# RECTANGLES ARE LEARNABLE

- Proof (cont.):

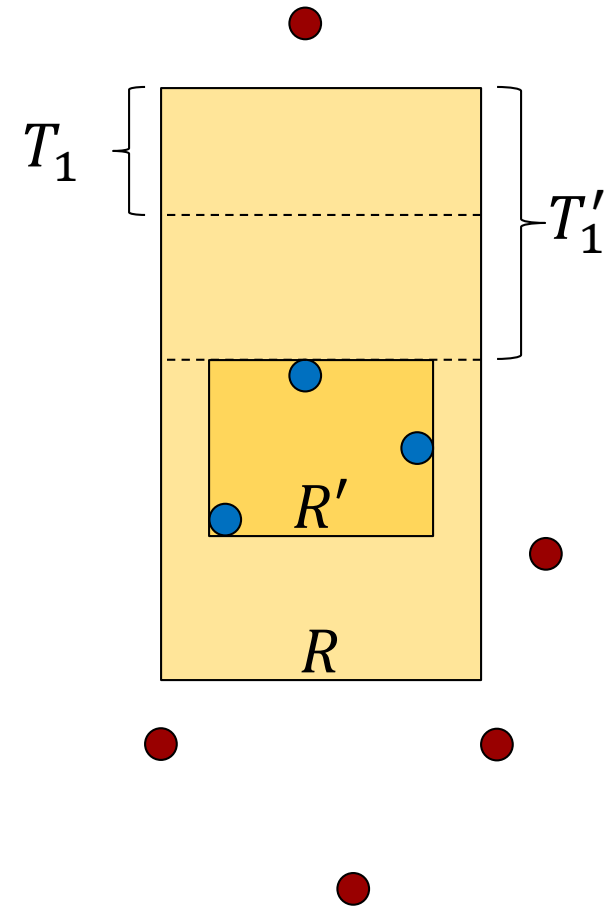
- Focusing wlog on  $T'_1$ , define a strip  $T_1$  such that  $w(T_1) = \frac{\epsilon}{4}$

- $w(T'_1) > \frac{\epsilon}{4} \Leftrightarrow T_1 \subsetneq T'_1$

- $T_1 \subsetneq T'_1 \Leftrightarrow x_1, \dots, x_m \notin T_1$

- $w(T'_1) > \frac{\epsilon}{4} \Leftrightarrow x_1, \dots, x_m \notin T_1$

- $\Pr[x_1, \dots, x_m \notin T_1] = \left(1 - \frac{\epsilon}{4}\right)^m$



# RECTANGLES ARE LEARNABLE

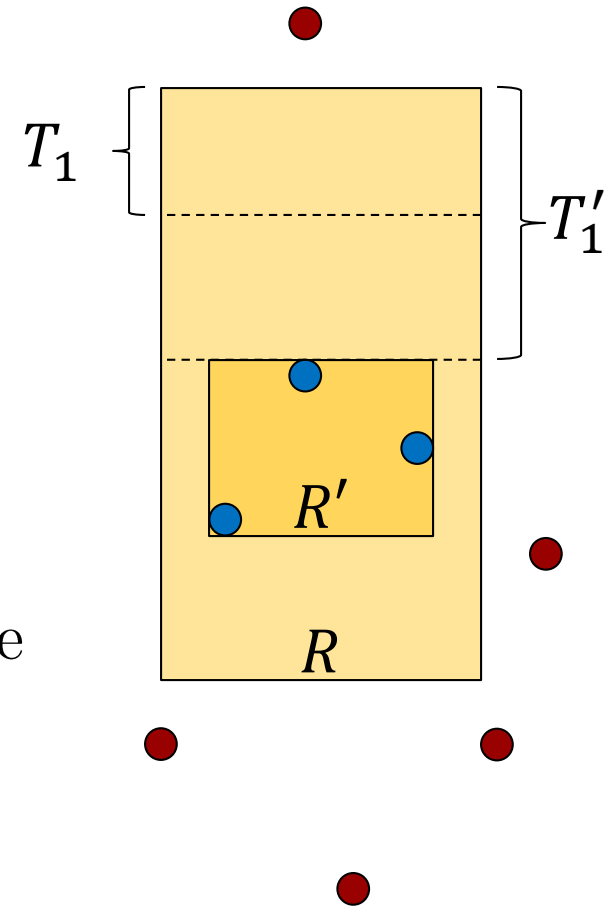
- Proof (cont.):

- $\Pr[w(R \setminus R') \geq \epsilon] \leq 4 \left(1 - \frac{\epsilon}{4}\right)^m$   
because at least one  $T'_i$  must have  $w(T'_i) \geq \epsilon/4$

- So we want

$$4 \left(1 - \frac{\epsilon}{4}\right)^m \leq 4 \left(e^{-\frac{\epsilon}{4}}\right)^m \leq \delta,$$

and with a bit of algebra we get the desired bound ■

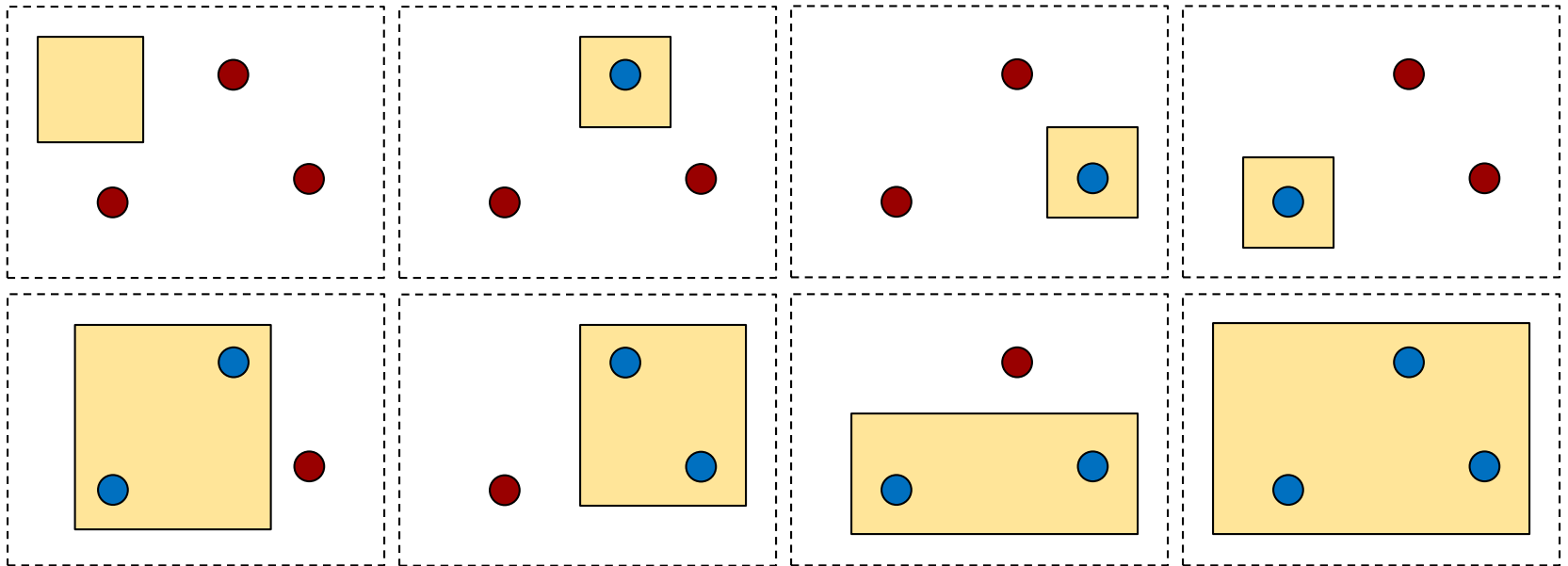


# VC DIMENSION

- We would like to obtain a more general result
- Let  $S = \{x_1, \dots, x_m\}$
- $\Pi_F(S) = \{(f(x_1), \dots, f(x_m)) : f \in F\}$




# VC DIMENSION



$$\Pi_F(S) = \{(-, -, -), (-, +, -), (-, -, +), (+, -, -), \\ (+, +, -), (-, +, +), (+, -, +), (+, +, +)\}$$

# VC DIMENSION

- $X =$  real line
- $F =$  intervals; points inside interval are labeled by  $+$ , outside by  $-$
- **Poll 1:** what is  $|\Pi_F(S)|$  for  $S =$  
- 1. 1
- 2. 2
- 3. 3
- 4. 4

# VC DIMENSION

• **Poll 2:** what is  $|\Pi_F(S)|$  for  $S =$  

1. 5

2. 6

3. 7

4. 8

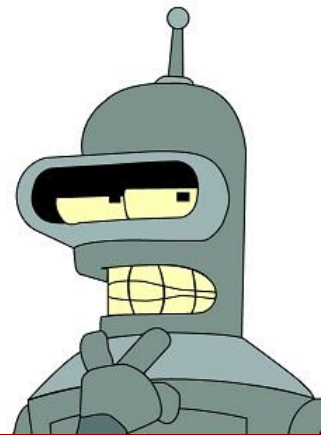




# VC DIMENSION

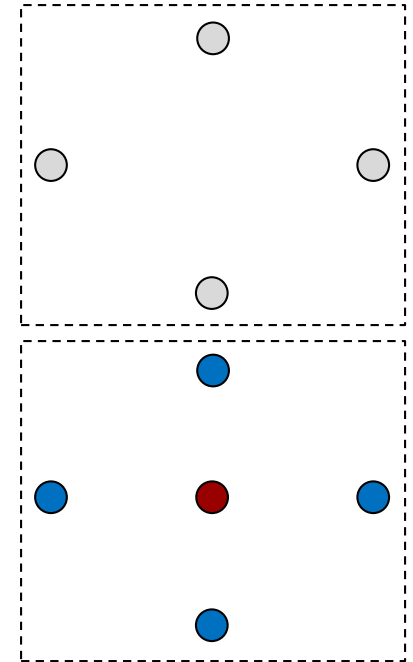
- $S$  is **shattered** by  $F$  if  $|\Pi_F(S)| = 2^{|S|}$
- The **VC dimension** of  $F$  is the cardinality of the largest set that is shattered by  $F$

How do we  
prove upper and  
lower bounds?



# EXAMPLE: RECTANGLES

- There is an example of four points that can be shattered
- For any choice of five points, one is “internal”
- A rectangle cannot label outer points by 1 and inner point by 0
- VC dimension is 4



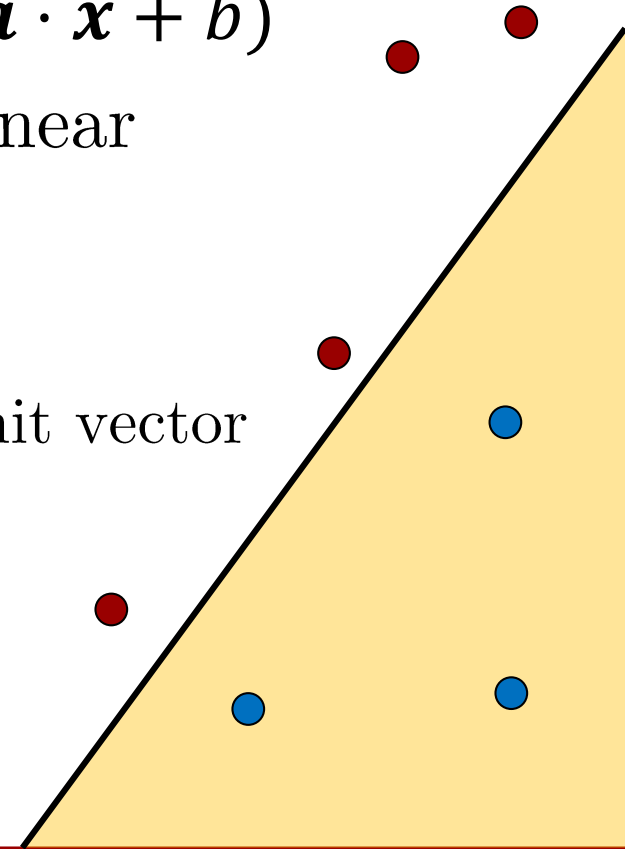
# VC DIMENSION

- **Poll 3:**  $X =$  real line,  $F =$  intervals, what is  $\text{VC-dim}(F)$ ?
  1. 1
  2. 2
  3. 3
  4. None of the above
- **Poll 4:**  $X =$  real line,  $F =$  unions of intervals, what is  $\text{VC-dim}(F)$ ?
  1. 2
  2. 3
  3. 4
  4. None of the above



# EXAMPLE: LINEAR SEPARATORS

- $X = \mathbb{R}^d$
- A linear separator is  $f(\mathbf{x}) = \text{sgn}(\mathbf{a} \cdot \mathbf{x} + b)$
- **Theorem:** The VC dimension of linear separators is  $d + 1$
- **Proof (lower bound):**
  - $\mathbf{e}^i = (0, \dots, 0, 1, 0, \dots, 0)$  is the  $i$ -th unit vector
  - $S = \{\mathbf{0}\} \cup \{\mathbf{e}^i : i = 1, \dots, d\}$
  - Given  $y^0, \dots, y^d \in \{-1, 1\}$ , set  $\mathbf{a} = (y^1, \dots, y^d), b = y^0/2$  ■

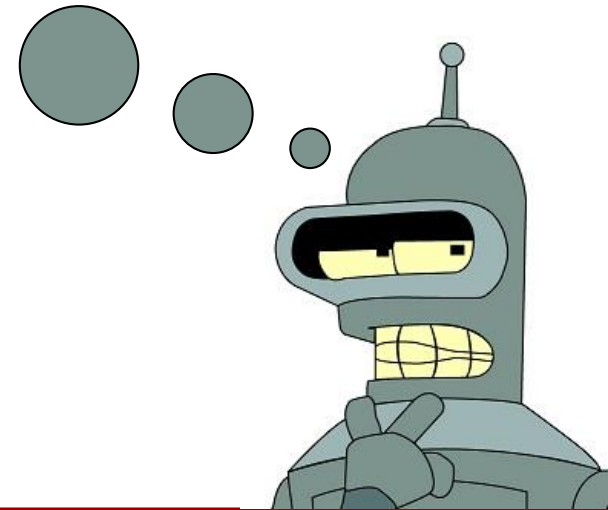


# SAMPLE COMPLEXITY

- If for any  $k$  there is a sample of size  $k$  that can be shattered by  $F$ , we say that  $\text{VC-dim}(F) = \infty$
- **Theorem:** A function class  $F$  with  $\text{VC-dim}(F) = \infty$  is not PAC learnable
- **Theorem:** Let  $F$  with  $\text{VC-dim}(F) = d$ . Let  $L$  be an algorithm that produces an  $f \in F$  that is **consistent** with the given samples  $S$ . Then  $L$  is a learning algorithm for  $F$  with sample complexity

$$m^*(\epsilon, \delta) = O\left(\frac{1}{\epsilon} \log \frac{1}{\delta} + \frac{d}{\epsilon} \log \frac{1}{\epsilon}\right)$$

Implications for  
linear classifiers?  
Overfitting?



# SUMMARY

- Definitions
  - PAC model
  - Error, accuracy, confidence
  - Learning algorithm
  - $\Pi_F(S)$ , shattering
  - VC-dimension
- Turing-award-winning ideas:
  - Learnability can be formalized

